


Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	64	(EDWARDS-ERIC-C or EDWARDS-ERIC or EDWARDS-ERIC-\$.in.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/09/13 09:30
L2	89	(CANADIAN and SPACE).as.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/09/13 09:30
L3	0	(xiphos).as.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/09/13 09:30
L4	2	xiphos	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/09/13 09:53
L5	7428	345/1.1,1.3,7,8,9,156,158,162,184,427,474,592,595,620,649.ccls.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/09/13 09:53
L6	3120	340/901,902,903,904,905,980.ccls.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/09/13 09:54

L7	1871	359/13,630,631,632,633.ccls.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 09:54
L8	5723	348/42,47,50,51,52,53,94, 115,117,123,129,130,135,139, 142,143,144,148,161,169,207. 11,208.2,208.4,208.14,211.7, 211.8,211.9,211.11,211.14, 376.ccls.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 10:04
L10	49116	motorola.as.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:08
L11	733735	((head or helmet or HMD) with (velocity or speed or acceleration or position or location or displacement or movement or rotation or orientation))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:08
L12	726	(telepresen\$4 or (tele adj presen\$4))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L13	84	(telepresen\$4 or (tele adj presen\$4)).ti.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09

L14	152	(telepresen\$4 or (tele adj presen\$4)).ab.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L15	9091	(camera and (((head or helmet) near mount\$3) or HMD))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L16	1530	(camera and (((head or helmet) near mount\$3) or HMD)).ab.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L17	5048	(camera same (((head or helmet) near mount\$3) or HMD))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L18	4181	(camera with (((head or helmet) near mount\$3) or HMD))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L19	172085	(time adj delay)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09

L20	24781	(stereoscopic or (stereo adj scopic))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L21	16526	(image near (offset\$4 or shift\$4))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L22	39547	((vertical and horizontal) with (offset\$4 or shift\$4))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L23	1507	((slave or slaved) with camera)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L24	548	(predetermined adj fill)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09
L25	10164	(pitch and roll and yaw)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:09

L26	10638	(range adj (sensor or detector))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:10
L27	15048	(motion near compensat\$3)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:10
L28	13036	(time near compensat\$3)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:10
L29	6331	("field of view" or FOV)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:10
L30	25667	(camera near (position or angle or direction or orientation))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:10
L31	12506	(camera near (move or moving or movement))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/09/13 12:10


9/13/05